



AiP33620

2-line Serial Interface/Common Cathode

8Seg 8Grid LED Controller/Driver

with Constant Current

Product Specification

Specification Revision History:

| Version | Date | Description |
|------------|---------|--|
| 2020-07-A1 | 2020-07 | New |
| 2021-12-A2 | 2021-12 | Modify Ordering Information |
| 2022-04-A3 | 2022-04 | Add SSOP20 reel packing specifications |
| 2023-03-B1 | 2023-03 | Update template |
| 2024-01-B2 | 2024-01 | Add QFN20 package form |
| 2024-04-B3 | 2024-04 | Modify the content |
| 2024-09-B4 | 2024-09 | Modify the parameter |
| 2025-03-B5 | 2025-03 | Modify the content |



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i-core



1. General Description

AiP33620 is an 8×8 dots matrix LED driver chip with constant current. It can be widely used in various monochromatic LED display systems or RGB full-color LED display systems.

Each LED can control the output effective time duty cycle through 8 bit data, so as to adjust the brightness of each LED by 256 steps.

MCU interface is integrated in the chip, which can be controlled by the master IC through the two-wire serial interface similar to IIC communication protocol.

AiP33620 integrates LED blanking function, which can effectively avoid abnormal display problems such as shadowing.

AiP33620 provides more display functions and its instruction set is compatible with traditional constant voltage LED products such as AiP1628 and AiP1640, making it convenient for software engineers to quickly transplant programs and shorten the development cycle of the solution.

Features:

- Supply voltage range: 4.5V to 5.5V
- 8-channel LED dot matrix driver with common cathode
- 8-channel anode constant current drive, the maximum output current is 30mA
- Support a maximum of 8×8 matrix scanning, a total of 64 LEDs
- Instruction set is compatible with traditional constant voltage LED products, making it convenient to quickly transplant programs and shorten the development cycle of the solution
- Single point adjustment, each point supports 256 steps of brightness adjustment
- Overall adjustment, 32 steps constant current regulation of the entire dot matrix synchronization
- Two-wire serial interface
- Built-in RC oscillation
- Built-in power on reset circuit
- Built-in low voltage reset circuit
- Built-in blanking circuit
- Packaging information: SOP20/SSOP20/QFN20(3*3)

**Ordering Information:****Tube packing specifications:**

| Part number | Packaging form | Marking code | Tube quantity | Boxed tube quantity | Boxed quantity | Notes |
|-----------------|----------------|--------------|----------------|---------------------|------------------|---|
| AiP33620SA20.TB | SOP20 | AiP33620 | 35 PCS/tube | 80 tube/box | 2800 PCS/box | Dimensions of plastic enclosure: 12.8mm×7.5mm Pin spacing: 1.27mm |
| AiP33620VB20.TB | SSOP20 | AiP33620 | 50 PCS/tube | 200 tube/box | 10000 PCS/box | Dimensions of plastic enclosure: 8.7mm×3.9mm Pin spacing: 0.635mm |

Reel packing specifications:

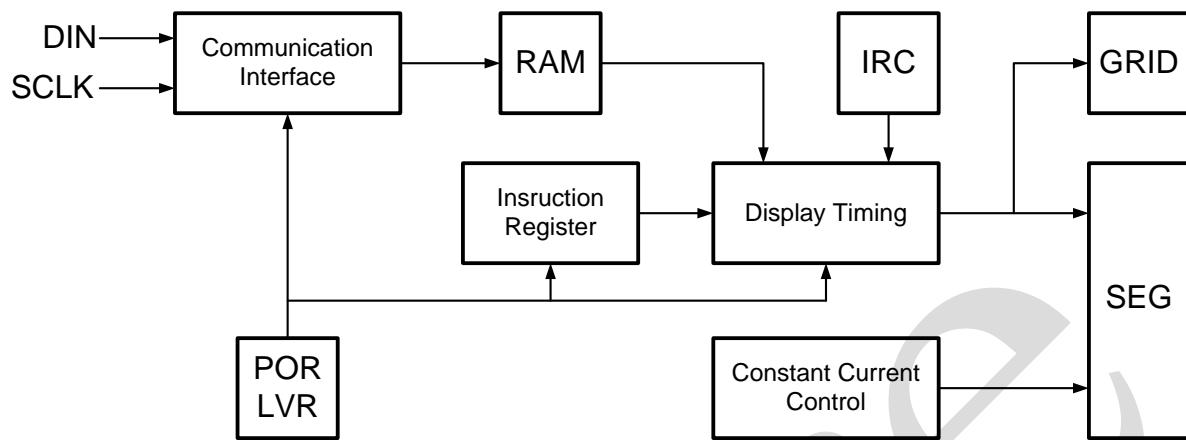
| Part number | Packaging form | Marking code | Reel quantity | Boxed reel quantity | Notes |
|-----------------|----------------|--------------|---------------|---------------------|---|
| AiP33620SA20.TR | SOP20 | AiP33620 | 2000PCS/reel | 2000PCS/box | Dimensions of plastic enclosure: 12.8mm×7.5mm Pin spacing: 1.27mm |
| AiP33620VB20.TR | SSOP20 | AiP33620 | 4000PCS/reel | 8000PCS/box | Dimensions of plastic enclosure: 8.7mm×3.9mm Pin spacing: 0.635mm |
| AiP33620QA20.TR | QFN20 | AiP33620 | 6000PCS/reel | 12000PCS/box | Dimensions of plastic enclosure: 3.0mm×3.0mm Pin spacing: 0.4mm |

Note: If the physical information is inconsistent with the ordering information, please refer to the actual product.

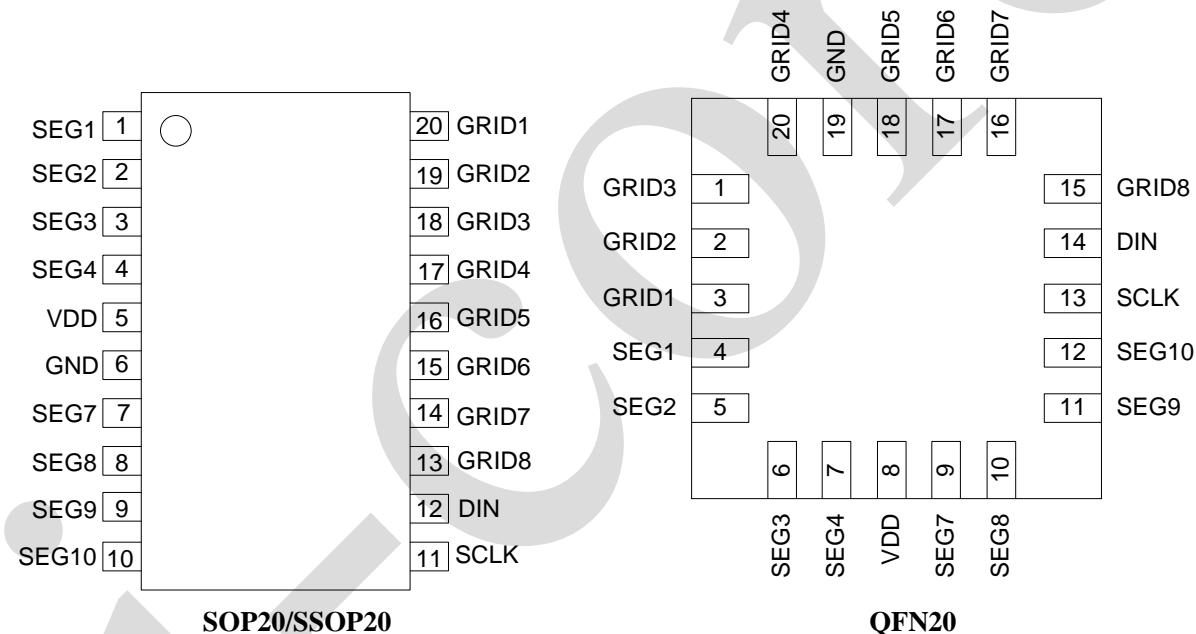


2、Block Diagram And Pin Description

2.1、Block Diagram



2.2、Pin Configurations





2.3、Pin Description

| Pin No. | | Pin Name | IO | Description |
|-----------------|-------|----------|----|--|
| SOP20 SSOP20 | QFN20 | | | |
| 1 | 4 | SEG1 | O | LED constant current drive, SEG output |
| 2 | 5 | SEG2 | O | LED constant current drive, SEG output |
| 3 | 6 | SEG3 | O | LED constant current drive, SEG output |
| 4 | 7 | SEG4 | O | LED constant current drive, SEG output |
| 5 | 8 | VDD | P | supply voltage |
| 6 | 19 | GND | P | ground |
| 7 | 9 | SEG7 | O | LED constant current drive, SEG output |
| 8 | 10 | SEG8 | O | LED constant current drive, SEG output |
| 9 | 11 | SEG9 | O | LED constant current drive |
| 10 | 12 | SEG10 | O | LED constant current drive |
| 11 | 13 | SCLK | I | serial interface clock |
| 12 | 14 | DIN | I | serial interface data |
| 13 | 15 | GRID8 | O | LED common port, GRID output |
| 14 | 16 | GRID7 | O | LED common port, GRID output |
| 15 | 17 | GRID6 | O | LED common port, GRID output |
| 16 | 18 | GRID5 | O | LED common port, GRID output |
| 17 | 20 | GRID4 | O | LED common port, GRID output |
| 18 | 1 | GRID3 | O | LED common port, GRID output |
| 19 | 2 | GRID2 | O | LED common port, GRID output |
| 20 | 3 | GRID1 | O | LED common port, GRID output |

Note: P: powered by; I: input; O: output; F: floating.

3、Electrical Parameter

3.1、Absolute Maximum Ratings

(T_{amb}=25°C, unless otherwise specified)

| Characteristic | Symbol | Conditions | Value | Unit |
|-----------------------|------------------|------------|--------------|------|
| supply voltage | VDD | - | -0.5~+7.0 | V |
| logic input voltage | V _{II} | - | -0.5~VDD+0.5 | V |
| SEG output current | I _{O1} | - | +30 | mA |
| GRID output current | I _{O2} | - | -300 | mA |
| power dissipation | P _D | - | 450 | mW |
| storage temperature | T _{stg} | - | -65~+150 | °C |
| soldering temperature | T _L | 10s | 260 | °C |

3.2、Recommended Operating Conditions

| Characteristic | Symbol | Min. | Typ. | Max. | Unit |
|--------------------------|------------------|---------|------|---------|------|
| logic supply voltage | VDD | 4.5 | 5 | 5.5 | V |
| HIGH-level input voltage | V _{IH} | 0.7×VDD | - | VDD | V |
| LOW-level input voltage | V _{IL} | 0 | - | 0.3×VDD | V |
| operating temperature | T _{amb} | -40 | - | +85 | °C |



3.3、Electrical Characteristics

3.3.1、DC Characteristics

($T_{amb}=25^{\circ}C$, $VDD=5V$, unless otherwise specified)

| Parameter | Symbol | Conditions | Min. | Typ. | Max. | Unit |
|-----------------------------|------------------|---------------------|---------|------|---------|------|
| logic supply voltage | VDD | - | 3 | 5 | 5.5 | V |
| Power on/off reset voltage | V _{PR} | - | - | 2 | - | V |
| HIGH-level input voltage | V _{IH} | - | 0.7×VDD | - | VDD | V |
| LOW-level input voltage | V _{IL} | - | 0 | - | 0.3×VDD | V |
| HIGH-level output current | I _{OH} | SEG Vo=VDD-1V | 28 | 30 | 32 | mA |
| LOW-level output current | I _{OL} | GRID Vo=0.3V | 250 | - | - | mA |
| HIGH-level input current | I _I | V _I =VDD | -1 | - | +1 | uA |
| input pull-up resistor | I _{RPH} | - | - | 10 | - | KΩ |
| dynamic current consumption | I _{DD} | - | - | - | 5 | mA |
| GRID scan time | T _{GST} | G_ST=00 | 185 | 285 | 385 | us |

3.3.2、AC Characteristics

($T_{amb}=25^{\circ}C$, $VDD=5V$, unless otherwise specified)

| Parameter | Symbol | Conditions | Min. | Typ. | Max. | Unit |
|-------------------------------|--------------------|----------------------|------|------|------|------|
| communication clock frequency | Fosc | SCLK, duty cycle=50% | - | 1 | - | MHz |
| data setup time | T _{setup} | - | 100 | - | - | ns |
| data hold time | T _{hold} | - | 100 | - | - | ns |
| propagation delay | T _{PLZ} | CLK→DIO CL=15pF | - | - | 300 | ns |
| | T _{PZL} | | - | - | 100 | ns |
| rise time of output voltage | T _{TZH} | CL=300pF, GRID | - | - | 2 | us |
| | | CL=300pF, SEG | - | - | 0.5 | us |
| fall time of output voltage | T _{THZ} | CL=300pF, GRID, SEG | - | - | 120 | us |



4. Function Description

4.1. Communication Interface

AiP33620 provides a simplified IIC communication interface with the following features:

- SCLK and DIN two-wire communication, port built-in 10KΩ pull-up resistance
- same start and stop signs as the standard IIC interface
- no slave address required
- no handshake signal ACK bit is required
- 8 clocks per cycle, high bit first

4.1.1. Start And Stop Signs

AiP33620 detects the start and stop signs when the clock signal is HIGH.

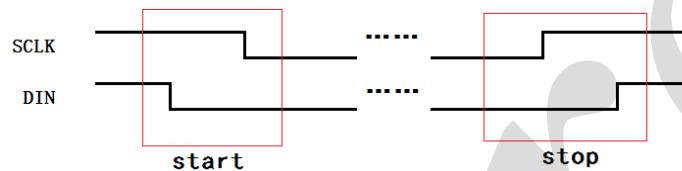


Figure 1. Start and stop signs waveforms

4.1.2. Single Byte Communication

The data can only be changed when the clock is LOW, otherwise there will be wrong start and stop signs. The waveform of single byte communication is shown in the figure below.

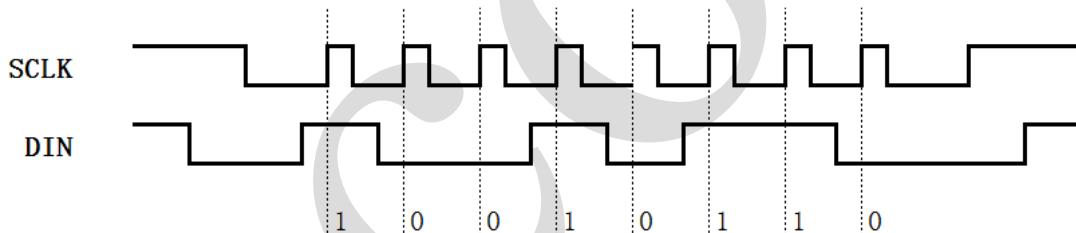


Figure 2. Single byte communication

Data is locked on the rising edge of the clock.

4.1.3. Multibyte Communication

AiP33620 can be used for multibyte continuous communication, that is, multiple bytes are continuously transmitted between a group of start and stop signs, as shown in the figure below.

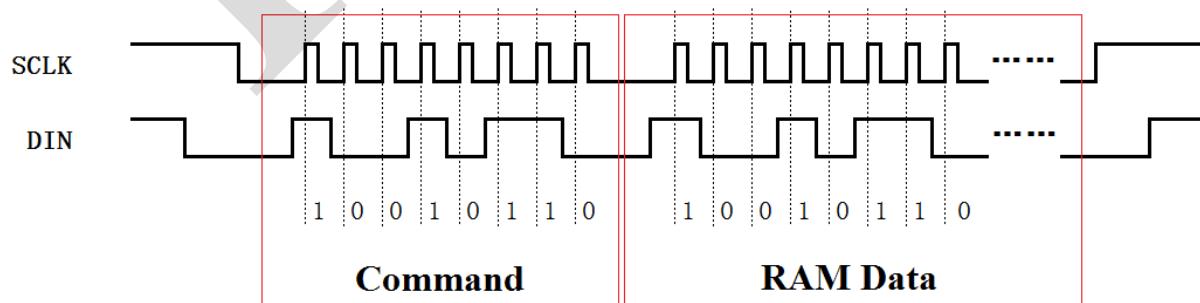


Figure 3. Two or more bytes of communication



In multibyte communication, the first byte is command, and the second byte is RAM data.

Starting from the second byte, the data will be stored in RAM from the address of 0x00.

4.2、Command System

4.2.1、Command Set

AiP33620 provides 5 commands for setting display related functions. The command set is as follows:

| Number | Command | B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|--------|----------------------------|----|----|---------------|--------------|-----|-------|-----------|-------------|
| 1 | constant current setting 1 | 0 | 0 | 0 | CURRENT[4:0] | | | | |
| 2 | constant current setting 2 | 0 | 0 | 1 | VGD | 0 | 0 | 0 | RAM_A DD[6] |
| 3 | dot matrix setting | 0 | 1 | G_N[2:0] | | | ADINC | T_E | T_S |
| 4 | display setting | 1 | 0 | G_ST[1:0] | | DIS | G_O | G_DT[1:0] | |
| 5 | RAM address setting | 1 | 1 | RAM_ADDR[5:0] | | | | | |

4.2.2、Constant Current Setting

| Number | Command | B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|--------|----------------------------|----|----|----|--------------|----|----|----|----|
| 1 | constant current setting 1 | 0 | 0 | 0 | CURRENT[4:0] | | | | |
| 2 | constant current setting 2 | 0 | 0 | 1 | VGD | 0 | 0 | 0 | X |

VGD:

Reset value: 0

When the current is less than 10mA, it is recommended to set it to 1, which can improve the current accuracy.

When the current is greater than 10mA, it is recommended to set it to 0, which can adapt to the saturation voltage drop of various LEDs under larger current conditions.

CURRENT[4:0]:

Reset value: 00000

Set SEG output constant current size, current calculation formula

$$I_{SEG}=6.75mA + CURRENT \times 0.745mA$$

The minimum setting is 00000, and the output instantaneous current is 6.75mA

The maximum setting is 11111, and the output instantaneous current is 29.85mA

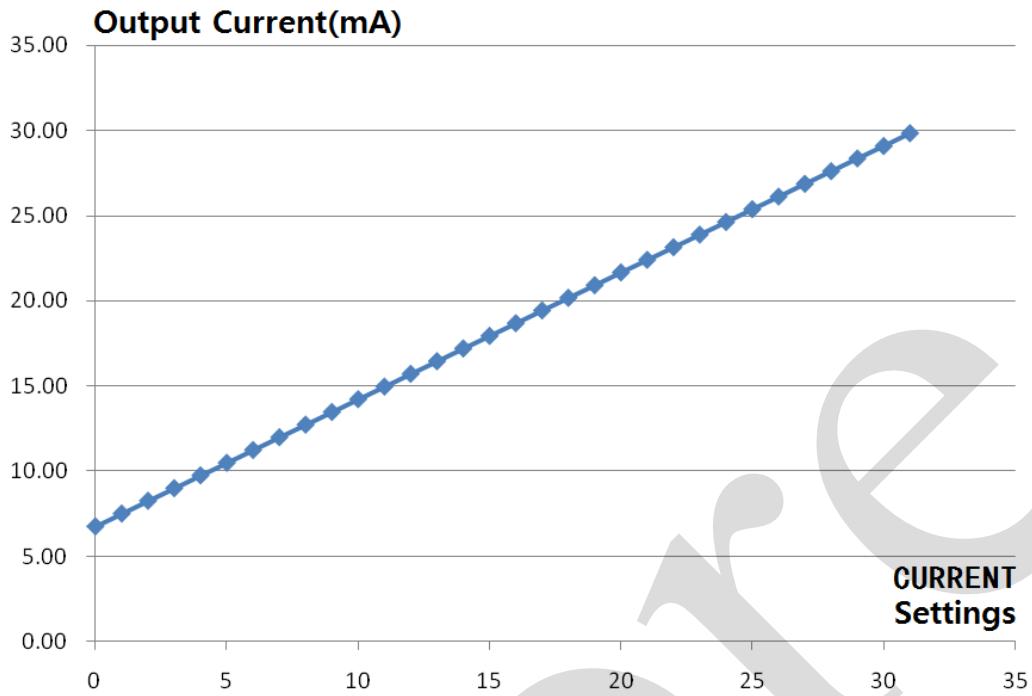


Figure 3. Relationship between CURRENT setting and SEG output current

Output average current needs to be calculated with G_N, G_DT and data in the RAM, refer to chapter “4.5、Calculation Of Output Average Current”.

4.2.3、Dot Matrix Setting

| Number | Command | B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|--------|--------------------|----|----|----|----------|----|-------|-----|-----|
| 3 | dot matrix setting | 0 | 1 | | G_N[2:0] | | ADINC | T_E | T_S |

G_N[2:0]:

Reset value: 000

Select the valid quantity of GRID:

| G_N[2:0] settings | Display format |
|-------------------|--------------------------------|
| 000 | GRID1 is valid, static display |
| 001 | GRID1~GRID2 are valid |
| 010 | GRID1~GRID3 are valid |
| 011 | GRID1~GRID4 are valid |
| 100 | GRID1~GRID5 are valid |
| 101 | GRID1~GRID6 are valid |
| 110 | GRID1~GRID7 are valid |
| 111 | GRID1~GRID8 are valid |

ADINC:

Reset value: 0

Set 0, when writing to RAM, the RAM address will be automatically increased after writing a byte, and the self adding range is controlled by G_N. After adding to the last address, it will return the address of 0x00, and then continue to increase automatically.



Set 1, the RAM address will not change when writing to RAM. At this time, the RAM address is controlled by RAM_ADDR of command number 5, and the operating range is not limited by G_N. The entire RAM space can always be operated.

T_E:

Reset value: 0

Set 0, work normally

Set 1, enter the test state, and the display is abnormal.

T_S:

Reset value: 0

Function control bit in test state, When T_E is set to 0, the value of T_S does not affect normal operation.

4.2.4、Display Setting

| Number | Command | B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|--------|-----------------|----|----|-----------|-----|-----|----|-----------|----|
| 4 | display setting | 1 | 0 | G_ST[1:0] | DIS | G_O | | G_DT[1:0] | |

FRAME[1:0]

Reset value: 00

Control GRID scan time, as shown in Figure 5

| G_ST[1:0] settings | GRID scan time |
|--------------------|----------------|
| 00 | 285.52us |
| 01 | 142.76us |
| 10 | 71.38us |
| 11 | 35.69us |

DIS:

Reset value: 0

SEG enable control bit

After setting 1, SEG can be displayed normally (* refer to “4.4、Operation Control Flow” for the process of enabling display)

G_O:

Reset value: 0

SEG port blanking function switch control.

Set 1, start SEG port blanking function

G_DT[1:0]:

Reset value: 00

GRID scan interval control, as shown in Figure 5

| G_DT[1:0] settings | GRID scan interval |
|--------------------|--------------------|
| 0x | 9/257 ×G_ST |
| 10 | 13/257 ×G_ST |
| 11 | 17/257 ×G_ST |

Within the scan interval, the circuit automatically performs the blanking operation of GRID port.

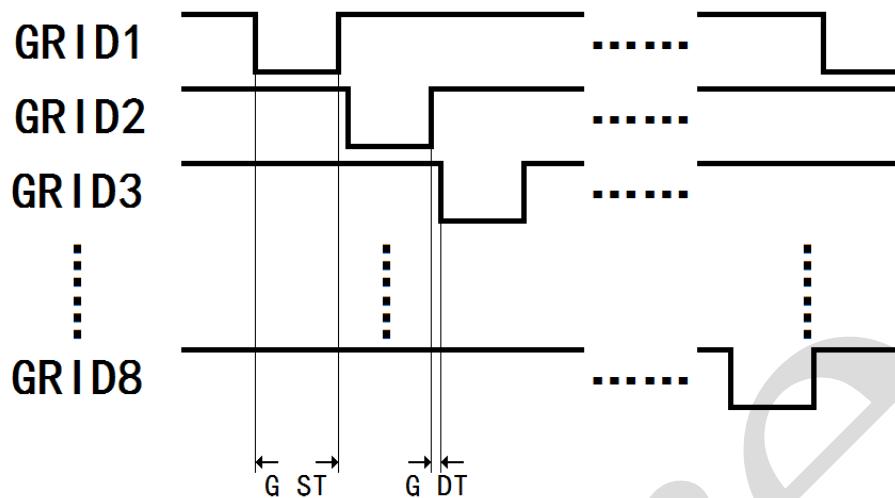


Figure 4. Schematic diagram of GRID scanning waveform

4.2.5、RAM Address Setting

| Number | Command | B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|--------|---------------------|----|----|----|----|---------------|----|----|----|
| 5 | RAM address setting | 1 | 1 | | | RAM_ADDR[5:0] | | | |

RAM_ADDR[5:0]

Reset value: 000 000

When ADINC=1, RAM_ADDR is used to set the operation address of RAM.

When ADINC=0, RAM_ADDR can be set by communication, but the set value has no effect.

4.3、RAM

AiP33620 has 64×8 bit RAM, which is used to store display data.

RAM has 64 addresses with 8 bit data for each address. The data of each address is used to control the output duty cycle of one LED. Based on the total time of a GRID active LOW, when the data is set to 0x00 in the RAM, the duty cycle of the corresponding LED lighting time is 0/257; when the data is set to 0xFF in the RAM, the duty cycle of the corresponding LED lighting time is 255/257.

The corresponding relationship between RAM address and LED dot matrix is as follows:

| Low Address High Address | xxxx_000 | xxxx_001 | xxxx_010 | xxxx_011 | xxxx_100 | xxxx_101 | xxxx_110 | xxxx_111 |
|-----------------------------|----------|----------|----------|----------|----------|----------|----------|----------|
| 0000_xxx | G1S1 | G2S1 | G3S1 | G4S1 | G5S1 | G6S1 | G7S1 | G8S1 |
| 0001_xxx | G1S2 | G2S2 | G3S2 | G4S2 | G5S2 | G6S2 | G7S2 | G8S2 |
| 0010_xxx | G1S3 | G2S3 | G3S3 | G4S3 | G5S3 | G6S3 | G7S3 | G8S3 |
| 0011_xxx | G1S4 | G2S4 | G3S4 | G4S4 | G5S4 | G6S4 | G7S4 | G8S4 |
| 0100_xxx | - | - | - | - | - | - | - | - |
| 0101_xxx | - | - | - | - | - | - | - | - |
| 0110_xxx | G1S7 | G2S7 | G3S7 | G4S7 | G5S7 | G6S7 | G7S7 | G8S7 |
| 0111_xxx | G1S8 | G2S8 | G3S8 | G4S8 | G5S8 | G6S8 | G7S8 | G8S8 |
| 1000_xxx | G1S9 | G2S9 | G3S9 | G4S9 | G5S9 | G6S9 | G7S9 | G8S9 |
| 1001_xxx | G1S10 | G2S10 | G3S10 | G4S10 | G5S10 | G6S10 | G7S10 | G8S10 |



Note: GnSn stands for cathode connected to GRIDn, anode connected to SEGn LED.

The RAM storage space of the address range 0x20~0x2F actually exists, and the address self increasing will also pass through these addresses. However, since there is no corresponding SEG driver port, writing data in this range will not affect the function of the circuit.

The corresponding relationship between the data in RAM and the duty cycle of LED lighting time:

| Data in RAM | Corresponding LED Lighting Time Duty Cycle |
|-------------|--|
| 0x00 | 0/257 |
| 0x01 | 1/257 |
| 0x02 | 2/257 |
| | |
| 0xFE | 254/257 |
| 0xFF | 255/257 |

If ADINC is set to 0, the RAM address of each write operation must start from 0x00, and the RAM address will be automatically increased by 1 after each address is written.

The range of RAM address self increasing will change with varies G_N[2:0] settings, according to G_N[2:0], AiP33620 skips unused RAM addresses.

If G_N[2:0]=111, the range of address self adding is 0x00~0x4F. When the address 0x4F is written, the address will return to 0x00 again.

If G_N[2:0]=110, the range of address self adding will automatically skip the address related to GRID8, that is, the address is automatically added from 0x00 to 0x06, followed by the address of 0x08~0x0E, followed by the address of 0x10~0x16, etc.

This feature makes it possible to refresh the graphic data of the whole dot matrix continuously without inserting additional data when setting a dot matrix of any size.

If ADINC is set to 1, the RAM address is controlled by RAM_ADDR[5:0] when writing to RAM. At this time, the RAM address will not be limited by G_N [2:0] settings. All addresses of the whole RAM can be accessed at any time.

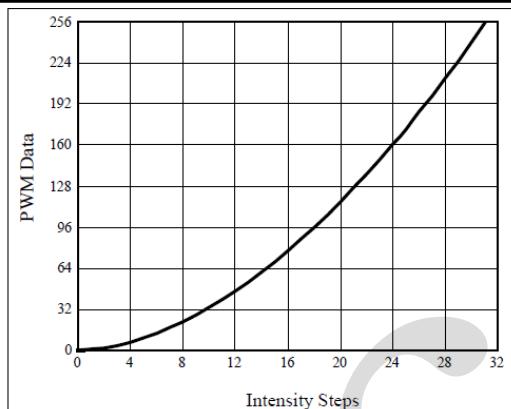
Because AiP33620 has 256 steps of PWM adjustment ability, the use of grayscale correction effect to control the PWM duty cycle change, can manually achieve the control effect similar to breathing light. This results in a reduced number of steps for the LED intensity setting, but causes the change in intensity to appear more linear to the human eye.

GAMMA correction, also known as GAMMA compression or encoding, is used to encode linear luminance to match the non-linear characteristics of display. Since AiP33620 has the function of adjusting PWM point by point, a GAMMA correction function can be applied when computing each subsequent LED intensity setting such that the changes in brightness matches the human eye's brightness curve.

Choosing more gamma steps provides for a more continuous looking breathing effect. This is useful for very long breathing cycles. The recommended configuration is defined by the breath cycle T. When T=1s, choose 32 gamma steps, when T=2s, choose 64 gamma steps. The user must decide the final number of gamma steps not only by the LED itself, but also based on the visual performance of the finished product. A breathing cycle refers to the time taken to complete a change from the darkest to the brightest (or vice versa).

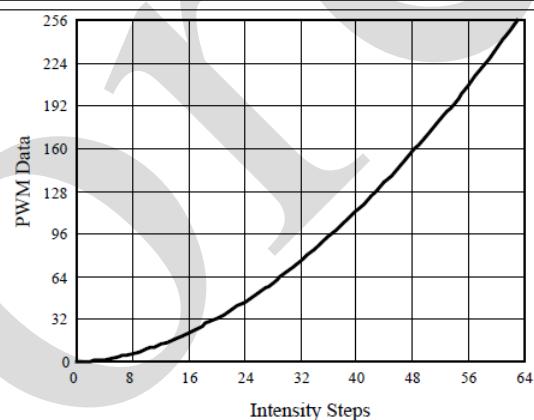


| C(0) | C(1) | C(2) | C(3) | C(4) | C(5) | C(6) | C(7) |
|-------|-------|-------|-------|-------|-------|-------|-------|
| 0 | 1 | 2 | 4 | 6 | 10 | 13 | 18 |
| C(8) | C(9) | C(10) | C(11) | C(12) | C(13) | C(14) | C(15) |
| 22 | 28 | 33 | 39 | 46 | 53 | 61 | 69 |
| C(16) | C(17) | C(18) | C(19) | C(20) | C(21) | C(22) | C(23) |
| 78 | 86 | 96 | 106 | 116 | 126 | 138 | 149 |
| C(24) | C(25) | C(26) | C(27) | C(28) | C(29) | C(30) | C(31) |
| 161 | 173 | 186 | 199 | 212 | 226 | 240 | 255 |



Gamma Correction (32 Steps)

| C(0) | C(1) | C(2) | C(3) | C(4) | C(5) | C(6) | C(7) |
|-------|-------|-------|-------|-------|-------|-------|-------|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| C(8) | C(9) | C(10) | C(11) | C(12) | C(13) | C(14) | C(15) |
| 8 | 10 | 12 | 14 | 16 | 18 | 20 | 22 |
| C(16) | C(17) | C(18) | C(19) | C(20) | C(21) | C(22) | C(23) |
| 24 | 26 | 29 | 32 | 35 | 38 | 41 | 44 |
| C(24) | C(25) | C(26) | C(27) | C(28) | C(29) | C(30) | C(31) |
| 47 | 50 | 53 | 57 | 61 | 65 | 69 | 73 |
| C(32) | C(33) | C(34) | C(35) | C(36) | C(37) | C(38) | C(39) |
| 77 | 81 | 85 | 89 | 94 | 99 | 104 | 109 |
| C(40) | C(41) | C(42) | C(43) | C(44) | C(45) | C(46) | C(47) |
| 114 | 119 | 124 | 129 | 134 | 140 | 146 | 152 |
| C(48) | C(49) | C(50) | C(51) | C(52) | C(53) | C(54) | C(55) |
| 158 | 164 | 170 | 176 | 182 | 188 | 195 | 202 |
| C(56) | C(57) | C(58) | C(59) | C(60) | C(61) | C(62) | C(63) |
| 209 | 216 | 223 | 230 | 237 | 244 | 251 | 255 |



Gamma Correction (64 Steps)

4.4、Operation Control Flow

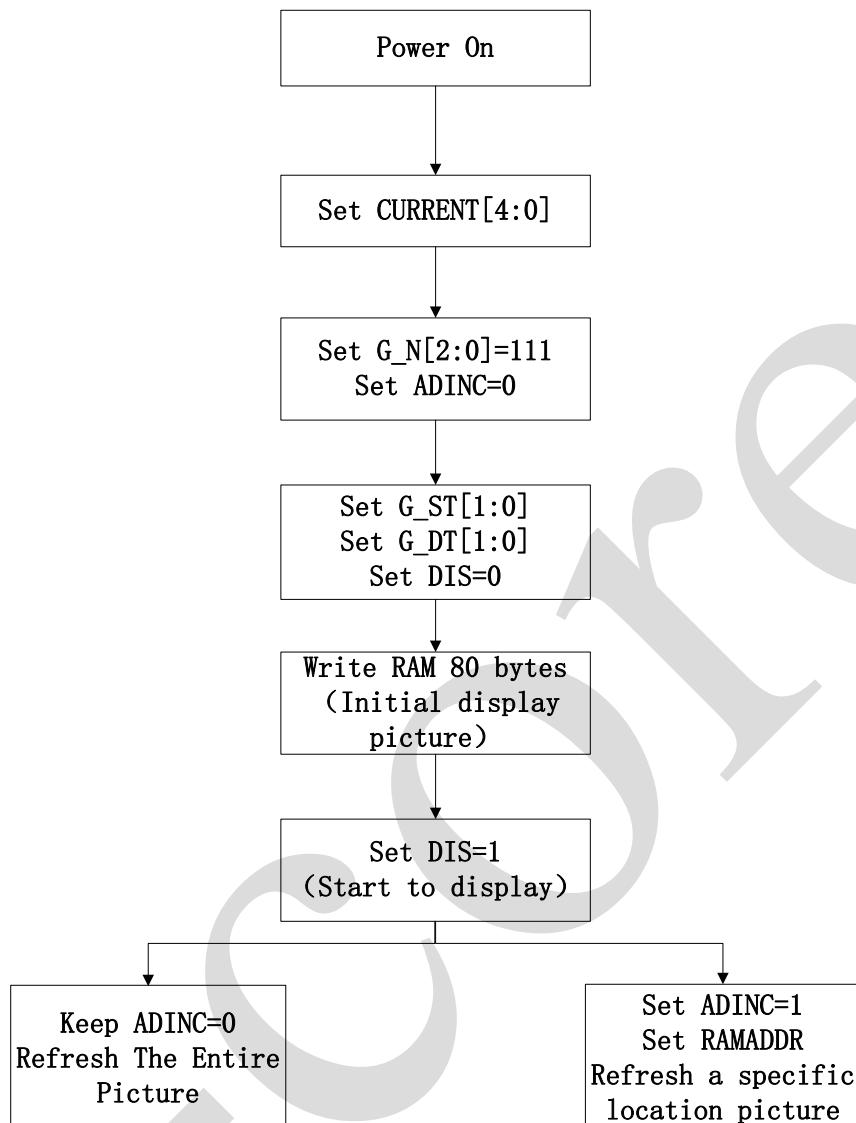


Figure 5. Recommended power on configuration process

In order to prevent the random display of LED dot matrix in the process of power on, AiP33620 has a certain prevention mechanism, which requires that 80 addresses of the entire RAM space must be filled when initializing the display graphics in the control process.

4.5、Calculation Of Output Average Current

If:

The instantaneous current set by CURRENT[4:0] is I_{MAX}

The number of valid GRID set by G_N [2:0] is n

The Scanning interval time set by G_DT [1:0] is a/257 × G_ST

The duty cycle of a LED in RAM is set to b/257 × G_ST

Then the average current on the corresponding LED is $I_{average} = I_{MAX} \times b / (n \times (257 + a))$

E. g:

CURRENT[4:0]=11111, i.e. $I_{MAX}=30mA$

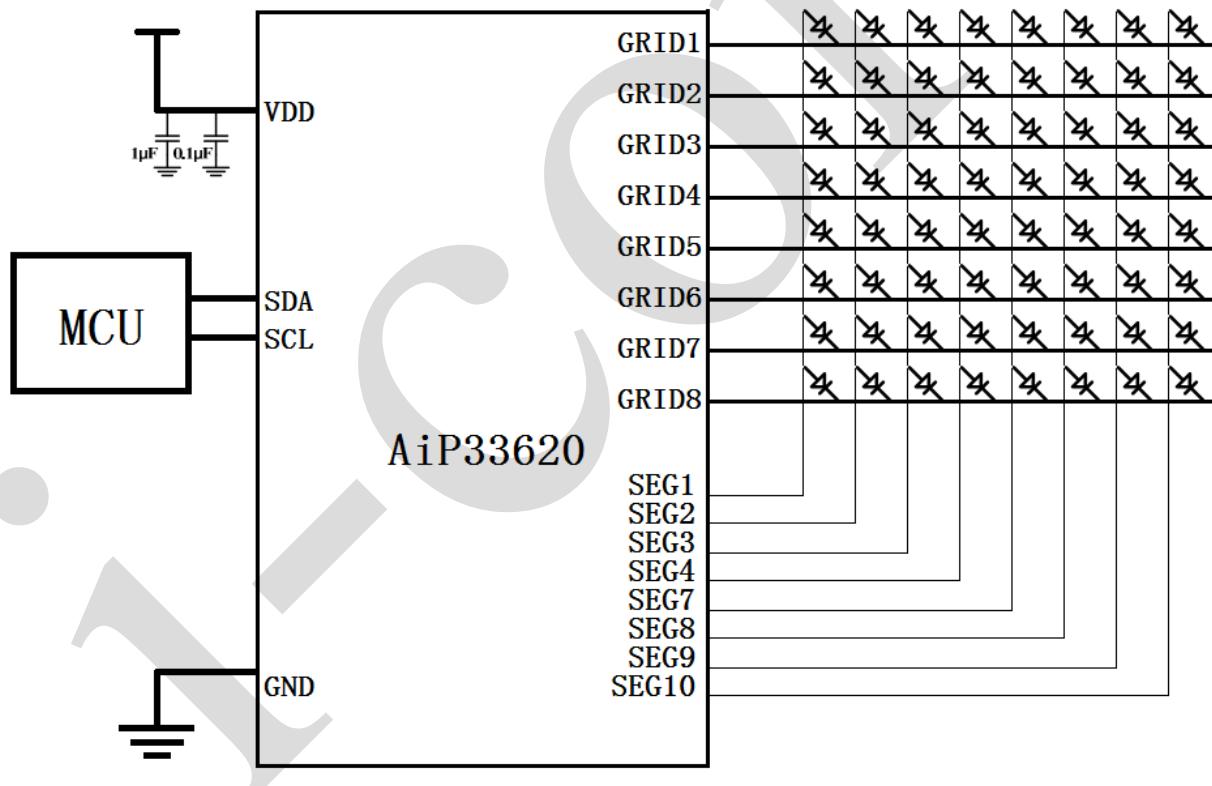
G_N[2:0]=111, that is, n=8

G_DT[1:0]=00, that is, a=9

Data in RAM is 0xFF, i.e. b=255

Then $I_{average}=30mA \times 255 / (8 \times (257+9))=3.595mA$

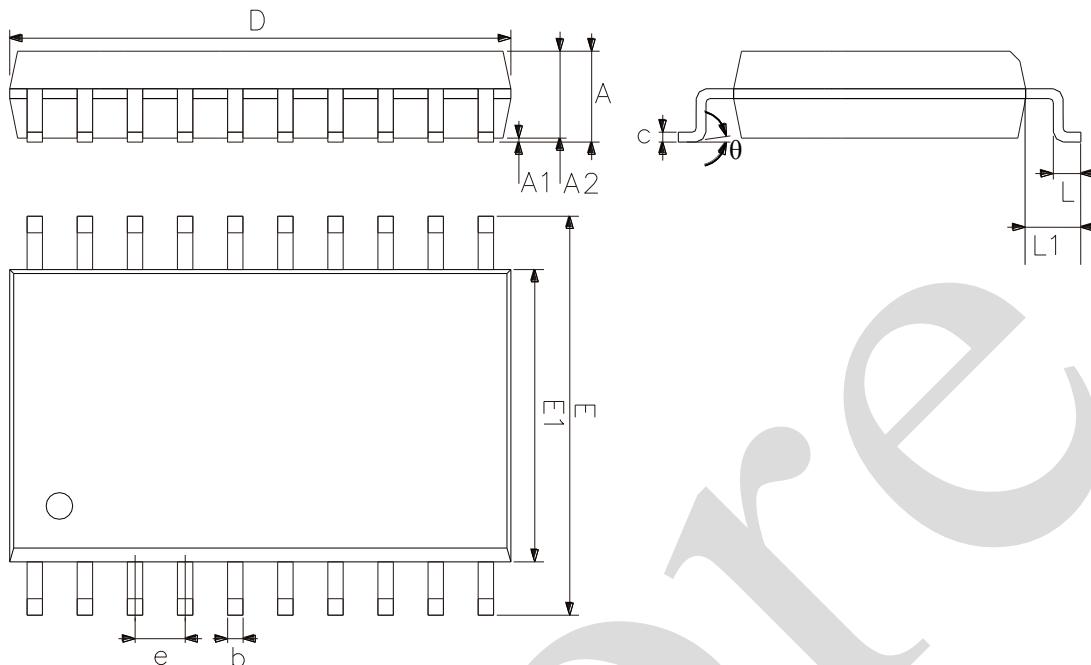
5、Typical Application Circuit And Application Note





6、Package Information

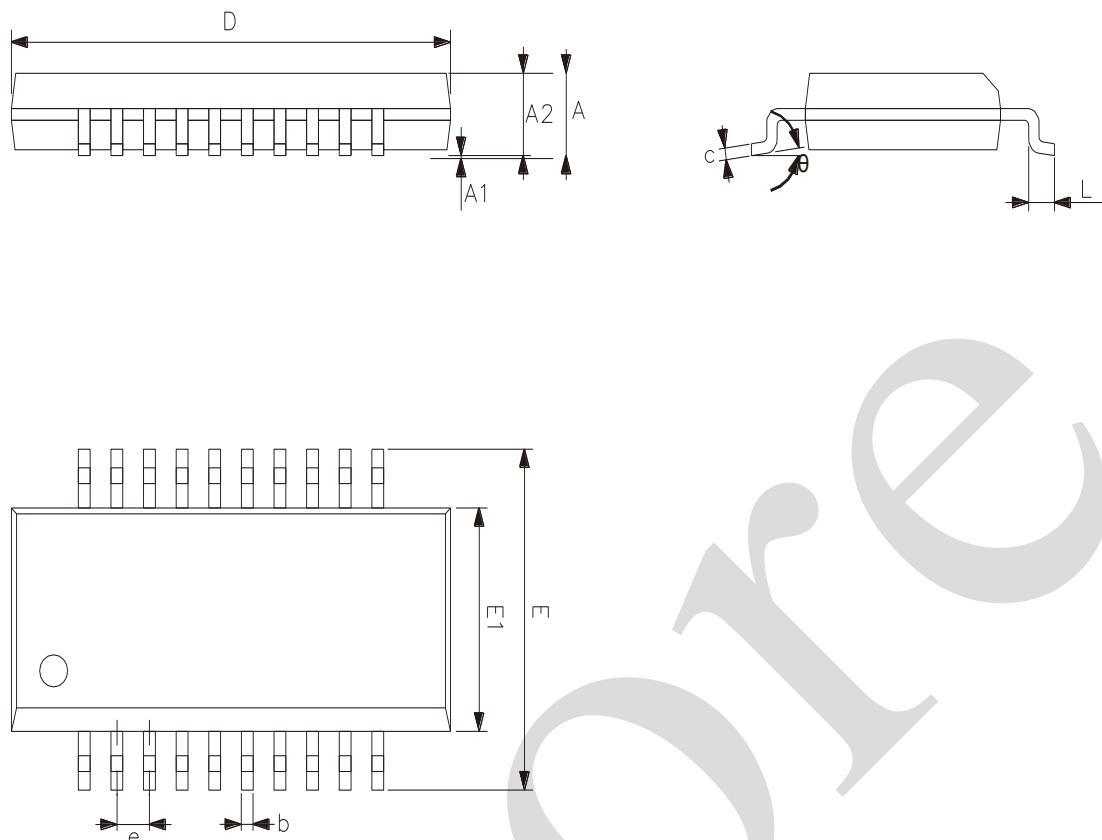
6.1、SOP20



| 2023/12/A | Dimensions In Millimeters | |
|-----------|---------------------------|-------|
| Symbol | Min. | Max. |
| A | 2.47 | 2.65 |
| A1 | 0.05 | 0.30 |
| A2 | 2.20 | 2.44 |
| b | 0.35 | 0.50 |
| c | 0.15 | 0.30 |
| D | 12.54 | 12.94 |
| E | 10.00 | 10.60 |
| E1 | 7.30 | 7.70 |
| e | 1.27 | |
| L | 0.40 | 1.05 |
| L1 | 1.30 | 1.50 |
| θ | 0 ° | 8 ° |

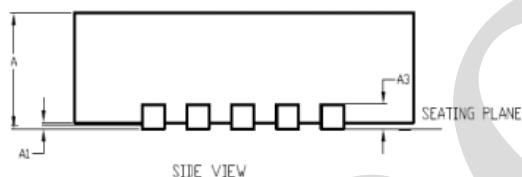
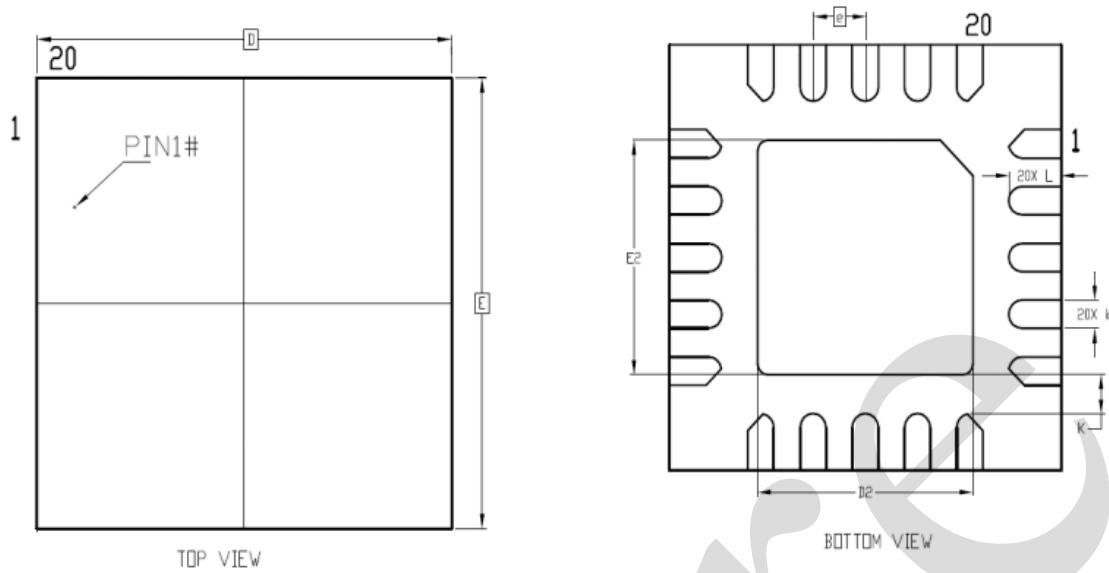


6.2、SSOP20



| 2023/12/A Dimensions In Millimeters | | |
|-------------------------------------|-------|------|
| Symbol | Min | Max |
| A | — | 1.75 |
| A1 | 0.10 | 0.25 |
| A2 | 1.30 | 1.55 |
| b | 0.23 | 0.31 |
| c | 0.19 | 0.25 |
| D | 8.50 | 8.75 |
| E | 5.80 | 6.20 |
| E1 | 3.80 | 4.00 |
| e | 0.635 | |
| L | 0.40 | 0.80 |
| θ | 0 ° | 8 ° |

6.3、QFN20 (3*3)



SIDE VIEW

| 2023/12/A | Dimensions In Millimeters | |
|-----------|---------------------------|------|
| Symbol | Min | Max |
| A | 0.70 | 0.80 |
| A1 | 0 | 0.05 |
| A3 | 0.18 | 0.25 |
| b | 0.15 | 0.25 |
| D | 2.90 | 3.10 |
| E | 2.90 | 3.10 |
| D2 | 1.55 | 1.75 |
| E2 | 1.55 | 1.75 |
| e | 0.40 | |
| L | 0.35 | 0.45 |



7、Statements And Notes

7.1、The name and content of Hazardous substances or Elements in the product

| Part name | Hazardous substances or Elements | | | | | | | | | |
|-------------------------|---|-------------------------------|-------------------------------|---------------------|--------------------------|--------------------------------|-------------------|-----------------------|---------------------------|----------------------|
| | Lead and lead compounds | Mercury and mercury compounds | Cadmium and cadmium compounds | Hexavalent chromium | Polybrominated biphenyls | Polybrominated biphenyl ethers | Dibutyl phthalate | Butylbenzyl phthalate | Di-2-ethylhexyl phthalate | Diisobutyl phthalate |
| Lead frame | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ |
| Plastic resin | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ |
| Chip | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ |
| The lead | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ |
| Plastic sheet installed | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ | ○ |
| explanation | ○: Indicates that the content of hazardous substances or elements in the detection limit of the following the SJ/T11363-2006 standard. ✕: Indicates that the content of hazardous substances or elements exceeding the SJ/T11363-2006 Standard limit requirements. | | | | | | | | | |

7.2、Notes

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